

Homework #2 Solution

Minho Kim

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Exercise 2.2

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$$\begin{aligned}
 & \left[\begin{array}{cccc|c} 1 & 1 & 1 & 1 & 4 \\ 1 & 2 & 3 & 4 & 10 \\ 1 & 3 & 6 & 10 & 20 \\ 1 & 4 & 10 & 20 & 35 \end{array} \right] \xrightarrow{\substack{R_2 - R_1 \\ R_3 - R_1 \\ R_4 - R_1}} \left[\begin{array}{cccc|c} 1 & 1 & 1 & 1 & 4 \\ 0 & 1 & 2 & 3 & 6 \\ 0 & 2 & 5 & 9 & 16 \\ 0 & 3 & 9 & 19 & 31 \end{array} \right] \\
 & \xrightarrow{\substack{R_1 - R_2 \\ R_3 - 2R_2 \\ R_4 - 3R_2}} \left[\begin{array}{cccc|c} 1 & 0 & -1 & -2 & -2 \\ 0 & 1 & 2 & 3 & 6 \\ 0 & 0 & 1 & 3 & 4 \\ 0 & 0 & 3 & 10 & 13 \end{array} \right] \\
 & \xrightarrow{\substack{R_1 + R_3 \\ R_2 - 2R_3 \\ R_4 - 3R_3}} \left[\begin{array}{cccc|c} 1 & 0 & 0 & 1 & 2 \\ 0 & 1 & 0 & -3 & -2 \\ 0 & 0 & 1 & 3 & 4 \\ 0 & 0 & 0 & 1 & 1 \end{array} \right] \\
 & \xrightarrow{\substack{R_1 - R_4 \\ R_2 + 3R_4 \\ R_3 - 3R_4}} \left[\begin{array}{cccc|c} 1 & 0 & 0 & 0 & 1 \\ 0 & 1 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 & 1 \\ 0 & 0 & 0 & 1 & 1 \end{array} \right]
 \end{aligned}$$

$$\rightarrow a = b = c = d = 1$$

39 We need to show that the linear system can be reduced to a reduced row echelon form with identity matrix on the left-side. **Since the coefficients are variables, we should be careful not to divide by zero.**

(a) $a \neq 0$

$$\begin{aligned}
 & \left[\begin{array}{cc|c} a & b & r \\ c & d & s \end{array} \right] \xrightarrow{R_1/a} \left[\begin{array}{cc|c} 1 & b/a & r/a \\ 0 & d - bc/a & s - cr/a \end{array} \right] \\
 & \xrightarrow{\substack{R_2 / \frac{ad-bc}{a} \\ R_1 - (b/a)R_2}} \left[\begin{array}{cc|c} 1 & 0 & \frac{r}{a} - \frac{b(as-cr)}{a(ad-bc)} \\ 0 & 1 & \frac{as-cr}{ad-bc} \end{array} \right]
 \end{aligned}$$

(b) $a = 0$

Note that $b \neq 0$ and $c \neq 0$ since $a = 0$ and $ad - bc \neq 0$.

$$\begin{aligned} & \xrightarrow{R_1 \leftrightarrow R_2} \left[\begin{array}{cc|c} c & d & r \\ 0 & b & s \end{array} \right] \\ & \xrightarrow{\substack{R_1/c \\ R_2/b}} \left[\begin{array}{cc|c} 1 & d/c & r/c \\ 0 & 1 & s/b \end{array} \right] \\ & \xrightarrow{R_1 - (d/c)R_2} \left[\begin{array}{cc|c} 1 & 0 & \frac{br-ds}{bc} \\ 0 & 1 & \frac{s}{b} \end{array} \right] \end{aligned}$$

51 Two equations are

$$\mathbf{u} \cdot \mathbf{x} = u_1x_1 + u_2x_2 + u_3x_3 = 0$$

and

$$\mathbf{v} \cdot \mathbf{x} = v_1x_1 + v_2x_2 + v_3x_3 = 0.$$

Therefore we have a (homogeneous) linear system with its augmented matrix

$$\left[\begin{array}{ccc|c} u_1 & u_2 & u_3 & 0 \\ v_1 & v_2 & v_3 & 0 \end{array} \right].$$

(a) $u_1 \neq 0$ or $v_1 \neq 0$

We can assume that $u_1 = 0$ since the case $v_1 \neq 0$ can be done in the same way.

$$\begin{aligned} \left[\begin{array}{ccc|c} u_1 & u_2 & u_3 & 0 \\ v_1 & v_2 & v_3 & 0 \end{array} \right] & \xrightarrow{\substack{R_1/u_1 \\ R_2 - v_1R_1}} \left[\begin{array}{ccc|c} 1 & u_2/u_1 & u_3/u_1 & 0 \\ 0 & v_2 - v_1u_2/u_1 & v_3 - v_1u_3/u_1 & 0 \end{array} \right] \\ & \xrightarrow{\substack{R_2 / \frac{u_1v_2 - u_2v_1}{u_1} \\ R_1 - \frac{u_2}{u_1}R_2}} \left[\begin{array}{ccc|c} 1 & 0 & \frac{u_3}{u_1} - \frac{u_2(u_1v_3 - u_3v_1)}{u_1(u_1v_2 - u_2v_1)} & 0 \\ 0 & 1 & -\frac{u_3v_1 - u_1v_3}{u_1v_2 - u_2v_1} & 0 \end{array} \right] \\ & = \left[\begin{array}{ccc|c} 1 & 0 & \frac{u_3(u_1v_2 - u_2v_1) - u_2(u_1v_3 - u_3v_1)}{u_1(u_1v_2 - u_2v_1)} & 0 \\ 0 & 1 & -\frac{u_3v_1 - u_1v_3}{u_1v_2 - u_2v_1} & 0 \end{array} \right] \\ & = \left[\begin{array}{ccc|c} 1 & 0 & -\frac{u_1(u_2v_3 - u_3v_2)}{u_1(u_1v_2 - u_2v_1)} & 0 \\ 0 & 1 & -\frac{u_3v_1 - u_1v_3}{u_1v_2 - u_2v_1} & 0 \end{array} \right] \\ & = \left[\begin{array}{ccc|c} 1 & 0 & -\frac{u_2v_3 - u_3v_2}{u_1v_2 - u_2v_1} & 0 \\ 0 & 1 & -\frac{u_3v_1 - u_1v_3}{u_1v_2 - u_2v_1} & 0 \end{array} \right] \end{aligned}$$

Therefore,

$$x_1 = \frac{u_2v_3 - u_3v_2}{u_1v_2 - u_2v_1}x_3 \quad \text{and} \quad x_2 = \frac{u_3v_1 - u_1v_3}{u_1v_2 - u_2v_1}x_3$$

hence

$$\mathbf{u} \times \mathbf{v} = \begin{bmatrix} \frac{u_2v_3 - u_3v_2}{u_1v_2 - u_2v_1}x_3 \\ \frac{u_3v_1 - u_1v_3}{u_1v_2 - u_2v_1}x_3 \\ x_3 \end{bmatrix} = \begin{bmatrix} u_2v_3 - u_3v_2 \\ u_3v_1 - u_1v_3 \\ u_1v_2 - u_2v_1 \end{bmatrix} \frac{x_3}{u_1v_2 - u_2v_1}.$$

(b) $u_1 = v_1 = 0$

Note that, in this case, either $u_2 \neq 0$ or $v_2 \neq 0$ since, if $u_2 = v_2 = 0$, \mathbf{u} and \mathbf{v} are parallel and the cross product is not defined.

$$\begin{aligned} \left[\begin{array}{ccc|c} 0 & u_2 & u_3 & 0 \\ 0 & v_2 & v_3 & 0 \end{array} \right] &\xrightarrow{\begin{array}{l} R_1/u_2 \\ R_2 - v_2R_1 \end{array}} \left[\begin{array}{ccc|c} 0 & 1 & u_3/u_2 & 0 \\ 0 & 0 & \frac{u_2v_3 - u_3v_2}{u_2} & 0 \end{array} \right] \\ &\xrightarrow{\begin{array}{l} R_2/\frac{u_2v_3 - u_3v_2}{u_2} \\ R_1 - \frac{u_3}{u_2}R_2 \end{array}} \left[\begin{array}{ccc|c} 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \end{array} \right] \end{aligned}$$

Therefore the solution is

$$x_2 = x_3 = 0$$

and

$$\mathbf{u} \times \mathbf{v} = \begin{bmatrix} x_1 \\ 0 \\ 0 \end{bmatrix}.$$

Since $u_1 = v_1 = 0$, (t is a free parameter)

$$\begin{bmatrix} u_2v_3 - u_3v_2 \\ u_3v_1 - u_1v_3 \\ u_1v_2 - u_2v_1 \end{bmatrix} t = \begin{bmatrix} u_2v_3 - u_3v_2 \\ 0 \\ 0 \end{bmatrix} t$$

therefore $\mathbf{u} \times \mathbf{v}$ is a multiple of $\begin{bmatrix} u_2v_3 - u_3v_2 \\ u_3v_1 - u_1v_3 \\ u_1v_2 - u_2v_1 \end{bmatrix}$.

Exercise 2.3

12 As Example 2.19, we show that any vector, say $\begin{bmatrix} a \\ b \\ c \end{bmatrix}$ in \mathbb{R}^3 can be written

as a linear combination of the tree vectors.

$$\begin{aligned}
 \left[\begin{array}{ccc|c} 1 & -1 & 2 & a \\ 2 & -1 & 1 & b \\ 3 & 0 & -1 & c \end{array} \right] & \xrightarrow{\substack{R_2 - 2R_1 \\ R_3 - 3R_1}} \left[\begin{array}{ccc|c} 1 & -1 & 2 & a \\ 0 & 1 & -3 & b - 2a \\ 0 & 3 & -7 & c - 3a \end{array} \right] \\
 & \xrightarrow{\substack{R_1 + R_2 \\ R_3 - 3R_2}} \left[\begin{array}{ccc|c} 1 & 0 & -1 & b - a \\ 0 & 1 & -3 & b - 2a \\ 0 & 0 & -1 & 3a - 3b + c \end{array} \right] \\
 & \xrightarrow{\substack{R_3/(-1) \\ R_1 + R_3 \\ R_2 + 3R_3}} \left[\begin{array}{ccc|c} 1 & 0 & 0 & -4a + 4b - c \\ 0 & 1 & 0 & -11a + 10b - 3c \\ 0 & 0 & 1 & -3a + 3b - c \end{array} \right]
 \end{aligned}$$

Therefore

$$\begin{bmatrix} a \\ b \\ c \end{bmatrix} = (-4a + 4b - c) \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} + (-11a + 10b - 3c) \begin{bmatrix} -1 \\ -1 \\ 0 \end{bmatrix} + (-3a + 3b - c) \begin{bmatrix} 2 \\ 1 \\ -1 \end{bmatrix}$$

and

$$\text{span} \left(\begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}, \begin{bmatrix} -1 \\ -1 \\ 0 \end{bmatrix}, \begin{bmatrix} 2 \\ 1 \\ -1 \end{bmatrix} \right) = \mathbb{R}^3.$$

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$$\begin{aligned}
 \mathbf{u} &= 1\mathbf{u} + 0(\mathbf{u} + \mathbf{v}) + 0(\mathbf{u} + \mathbf{v} + \mathbf{w}) \\
 \mathbf{v} &= (-1)\mathbf{u} + 1(\mathbf{u} + \mathbf{v}) + 0(\mathbf{u} + \mathbf{v} + \mathbf{w}) \\
 \mathbf{w} &= 0\mathbf{u} + (-1)(\mathbf{u} + \mathbf{v}) + 1(\mathbf{u} + \mathbf{v} + \mathbf{w})
 \end{aligned}$$

43 (a) The three vectors are linearly independent if and only if the equation

$$c_1(\mathbf{u} + \mathbf{v}) + c_2(\mathbf{v} + \mathbf{w}) + c_3(\mathbf{u} + \mathbf{w}) = \mathbf{0}$$

is satisfied for $c_1 = c_2 = c_3 = 0$. Now

$$c_1(\mathbf{u} + \mathbf{v}) + c_2(\mathbf{v} + \mathbf{w}) + c_3(\mathbf{u} + \mathbf{w}) = (c_1 + c_3)\mathbf{u} + (c_1 + c_2)\mathbf{v} + (c_2 + c_3)\mathbf{w} = \mathbf{0}$$

only when

$$c_1 + c_3 = 0 \quad \text{and} \quad c_1 + c_2 = 0 \quad \text{and} \quad c_2 + c_3 = 0$$

since \mathbf{u}, \mathbf{v} , and \mathbf{w} are linearly independent. It is straightforward to show that the solution of the linear system

$$\begin{aligned}
 c_1 & & + c_3 & = 0 \\
 c_1 & + c_2 & & = 0 \\
 & c_2 & + c_3 & = 0
 \end{aligned}$$

is $c_1 = c_2 = c_3 = 0$. Therefore the three vectors are linearly independent.

(b) In the same way,

$$c_1(\mathbf{u}-\mathbf{v})+c_2(\mathbf{v}-\mathbf{w})+c_3(\mathbf{u}-\mathbf{w}) = (c_1+c_3)\mathbf{u}+(-c_1+c_2)\mathbf{v}+(-c_2-c_3)\mathbf{w} = \mathbf{0}$$

if and only if the following linear system has solution.

$$\begin{array}{rcccc} c_1 & & & + & c_3 & = & 0 \\ -c_1 & + & c_2 & & & = & 0 \\ & & -c_2 & - & c_3 & = & 0 \end{array}$$

It is straight forward to show that the above linear system has a solution $c_1 = c_2 = c_3 = 0$ therefore the three vectors are linearly independent.

Exercise 2.4

6 Let the number of bags for house blend, special blend, and gourmet blend x , y , and z , respectively. Then

$$\begin{array}{rcccc} 300x & + & 200y & + & 100z & = & 30,000 & \text{(Colombian beans)} \\ 50x & + & 200y & + & 350z & = & 15,000 & \text{(Kenyan beans)} \\ 150x & + & 100y & + & 50z & = & 15,000 & \text{(French roast)} \end{array}$$

$$\begin{array}{l} \left[\begin{array}{ccc|c} 300 & 200 & 100 & 30000 \\ 50 & 200 & 350 & 15000 \\ 150 & 100 & 50 & 15000 \end{array} \right] \xrightarrow{\begin{array}{l} R_1/300 \\ R_2 - 50R_1 \\ R_3 - 150R_1 \end{array}} \left[\begin{array}{ccc|c} 1 & 2/3 & 1/3 & 100 \\ 0 & 500/3 & 1000/3 & 10000 \\ 0 & 0 & 0 & 0 \end{array} \right] \\ \xrightarrow{\begin{array}{l} R_2/(500/3) \\ R_1 - (2/3)R_2 \end{array}} \left[\begin{array}{ccc|c} 1 & 0 & -1 & 60 \\ 0 & 1 & 2 & 60 \\ 0 & 0 & 0 & 0 \end{array} \right] \end{array}$$

The solution is

$$\begin{array}{l} x = t + 60 \\ y = 60 - 2t \\ z = t \end{array}$$

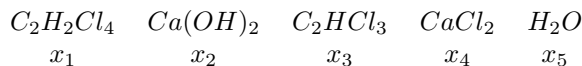
The overall profit is

$$0.50x + 1.50y + 2.00z = 0.50((t + 60) + 3(60 - 2t) + 4t) = 0.50(240 - t)$$

which is maximized when $t = 0$. Therefore the profit is maximized when

$$\begin{array}{l} x = 60 \\ y = 60 \\ z = 0. \end{array}$$

14 Let the amount of each molecules as follows:



Then we get the linear system for each atom as follows:

$$\begin{array}{l} C : 2x_1 \qquad \qquad \qquad = 2x_3 \\ H : 2x_1 + 2x_2 \qquad \qquad = x_3 \qquad \qquad \qquad + 2x_5 \\ Cl : 4x_1 \qquad \qquad \qquad = 3x_3 + 2x_4 \\ Ca : \qquad \qquad x_2 \qquad \qquad = \qquad \qquad \qquad x_4 \\ O : \qquad \qquad 2x_2 \qquad \qquad = \qquad \qquad \qquad \qquad \qquad x_5 \end{array}$$

which can be converted to a homogeneous linear system

$$A\mathbf{x} := \begin{bmatrix} 2 & -2 & & & \\ 2 & 2 & -1 & & -2 \\ 4 & & -3 & -2 & \\ & 1 & & -1 & \\ & 2 & & & -1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{bmatrix} = \mathbf{0}.$$

Using GNU Octave, we can get the reduced row echelon form of A as follows

$$\begin{bmatrix} 1 & & & -1 \\ & 1 & & -1/2 \\ & & 1 & -1 \\ & & & 1 & -1/2 \end{bmatrix}$$

Therefore, with $x_5 = t$ as the free parameter, the solution is

$$\mathbf{x} = \begin{bmatrix} t \\ 1/2t \\ t \\ 1/2t \\ t \end{bmatrix} = \begin{bmatrix} 1 \\ 1/2 \\ 1 \\ 1/2 \\ 1 \end{bmatrix} t$$

and the simplest form of solution is

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{bmatrix} = \begin{bmatrix} 2 \\ 1 \\ 2 \\ 1 \\ 2 \end{bmatrix}.$$

16 (a) By the conservation law, we can set up the equations at each intersection as follows

intersection	flow-in	=	flow-out
$A :$	$10 + 10$	$=$	$f_1 + f_2$
$B :$	$f_1 + f_3$	$=$	$20 + 5$
$C :$	$f_2 + f_4$	$=$	$15 + 10$
$D :$	$15 + 15$	$=$	$f_3 + f_4$

which can be converted to the linear system

$$A\mathbf{x} = \begin{bmatrix} 1 & 1 & & \\ 1 & & 1 & \\ & 1 & & 1 \\ & & 1 & 1 \end{bmatrix} \begin{bmatrix} f_1 \\ f_2 \\ f_3 \\ f_4 \end{bmatrix} = \begin{bmatrix} 20 \\ 25 \\ 25 \\ 30 \end{bmatrix}.$$

A can be converted to a reduced row echelon form as follows:

$$\begin{aligned} \left[\begin{array}{cccc|c} 1 & 1 & & & 20 \\ 1 & & 1 & & 25 \\ & 1 & & 1 & 25 \\ & & 1 & 1 & 30 \end{array} \right] & \xrightarrow{R_2 - R_1} \left[\begin{array}{cccc|c} 1 & 1 & & & 20 \\ & -1 & 1 & & 5 \\ & 1 & & 1 & 25 \\ & & 1 & 1 & 30 \end{array} \right] \\ & \xrightarrow{\begin{array}{l} (-1)R_2 \\ R_1 - R_2 \\ R_3 - R_2 \end{array}} \left[\begin{array}{cccc|c} 1 & & 1 & & 25 \\ & 1 & -1 & & -5 \\ & & 1 & 1 & 30 \\ & & 1 & 1 & 30 \end{array} \right] \\ & \xrightarrow{\begin{array}{l} R_1 - R_3 \\ R_2 + R_3 \\ R_4 - R_3 \end{array}} \left[\begin{array}{cccc|c} 1 & & & -1 & -5 \\ & 1 & & 1 & 25 \\ & & 1 & 1 & 30 \\ & & & 1 & 0 \end{array} \right]. \end{aligned}$$

Therefore, with $f_4 = t$ as the free parameters, the solution is

$$\begin{bmatrix} f_1 \\ f_2 \\ f_3 \\ f_4 \end{bmatrix} = \begin{bmatrix} t - 5 \\ 25 - t \\ 30 - t \\ t \end{bmatrix} = \begin{bmatrix} 1 \\ -1 \\ -1 \\ 1 \end{bmatrix} t + \begin{bmatrix} -5 \\ 25 \\ 30 \\ 0 \end{bmatrix}.$$

(b) If $f_4 = 10$ then $t = 10$ therefore the solution is

$$\begin{bmatrix} f_1 \\ f_2 \\ f_3 \\ f_4 \end{bmatrix} = \begin{bmatrix} 5 \\ 15 \\ 20 \\ 10 \end{bmatrix}.$$

(c) Keeping in mind that any flow should have nonnegative value,

$$\begin{aligned} f_1 = t - 5 \geq 0 & \rightarrow t \geq 5 \\ f_2 = 25 - t \geq 0 & \rightarrow t \leq 25 \\ f_3 = 30 - t \geq 0 & \rightarrow t \leq 30 \\ f_4 = t \geq 0 & \rightarrow t \geq 0 \end{aligned}$$

Overall, the range of t is

$$5 \leq t \leq 25$$

hence the range of each flow is

$$\begin{aligned} 0 &\leq f_1 \leq 20 \\ 0 &\leq f_2 \leq 20 \\ 5 &\leq f_3 \leq 25 \\ 5 &\leq f_4 \leq 25 \end{aligned}$$

- (d) We can easily flip the direction of each flow by allowing nonpositive values for each flow. Therefore,

$$\begin{aligned} f_1 = t - 5 \leq 0 &\rightarrow t \leq 5 \\ f_2 = 25 - t \leq 0 &\rightarrow t \geq 25 \\ f_3 = 30 - t \leq 0 &\rightarrow t \geq 30 \\ f_4 = t \leq 0 &\rightarrow t \leq 0 \end{aligned}$$

Since there is no t satisfying all the conditions, the system has no solution.

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$$\begin{aligned} &A(x-1)(x^2+x+1)(x^2+1)^3 + Bx(x^2+x+1)(x^2+1)^3 + (Cx+D)x(x-1)(x^2+1)^3 \\ &+ (Ex+F)x(x-1)(x^2+x+1)(x^2+1)^2 + (Gx+H)x(x-1)(x^2+x+1)(x^2+1) \\ &+ (Ix+J)x(x-1)(x^2+x+1) \end{aligned}$$

Exercise 2.5

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